

Help, It looks Confusing:

GUI Task Automation Through Demonstration and Follow-up Questions

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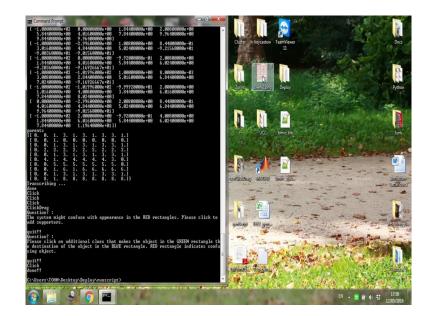
Target Users:

People Who Want To ...

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(Linear) Have a macro/script where one click does many actions.

Example: switch everything to high contrast mode.



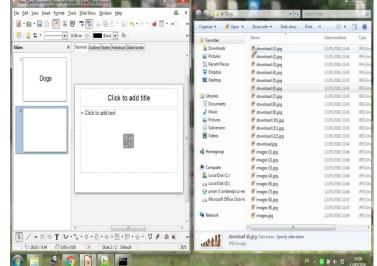
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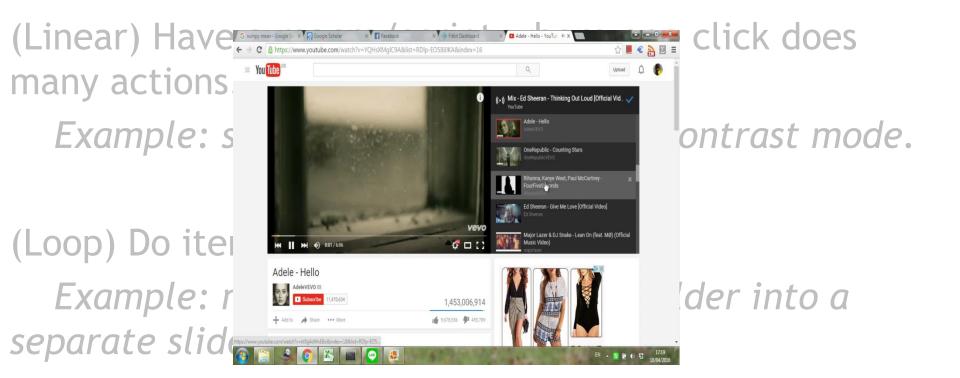
Example: switch everything to high contrast mode.

(Loop) Do iterative tasks, automatically.

Example: make each photo in this folder into a separate slide in PowerPoint.



Target Users: People Who Want To ...



(Monitoring) React the same way each time ... Example: click the "skip ad" during a youtube video.

Before HILC

Before HILC

- Nearest neighbors : Programming by Demonstration
 - Sikuli, Sikuli Slides (Yeh et al 2009).
 - Koala (Little et al 2007), CoScripter (Leshed et al 2008).
 - More systems can be found in "Watch what I do" (Cypher and Halbert 1993).

	Domain Independent	No Programming Skill Required	Deal with Non-linear Tasks
Sikuli			
Sikuli Slides			
Koala, CoScriptor			
Sheepdog, Familiar			
HILC	S		

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Before HILC

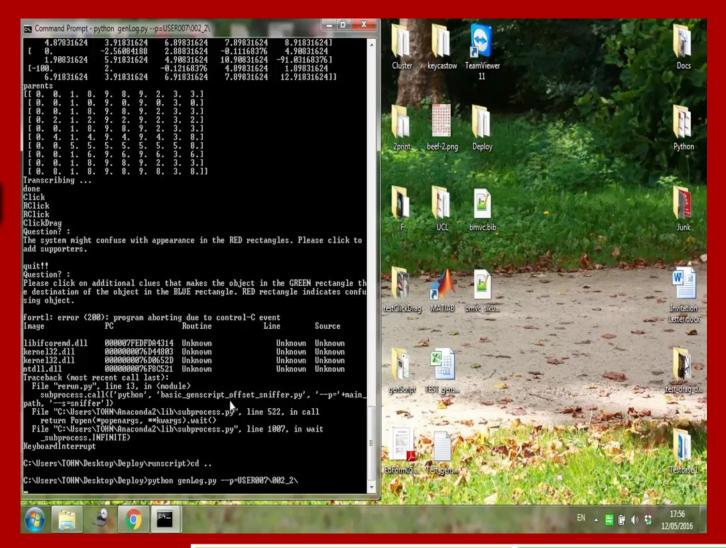
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- Differences :
 - HILC is software-agnostic; no need for Accessibility API's and works across applications.
 - Inputs users feed to HILC resemble how a human teaches another to complete a task.
 - Able to deal with non-linear task.

Phase A. HILC observes a user¹ demonstrating a task.

Phase B. HILC <u>asks a user²</u> to clarify confusing steps, if any, and then <u>synthesizes a task script</u>.

Phase C. A user³ <u>triggers</u> the script to complete the task.

From User's Perspective Phase A. HILC observes a user¹ demonstrating a task.









From User's Perspective Phase B. HILC <u>asks a user²</u> to clarify confusing steps.

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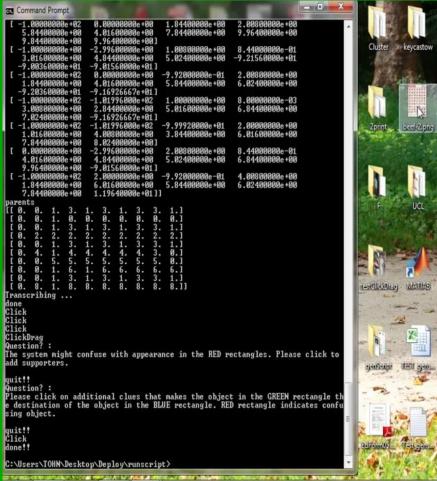








From User's Perspective Phase C. A user³ triggers the script to complete the task.









Teacher



12/05/2010

From development perspective

Phases

Task Classification

	Linear	Looping	Monitoring
A: Demonstration	Normal	+Signal	+Signal
B: Teaching	Supporters	Positives False positives Supporters	Visual Cues
C: Running	Execute	Execute	Execute

Phase A : Demonstration Phase

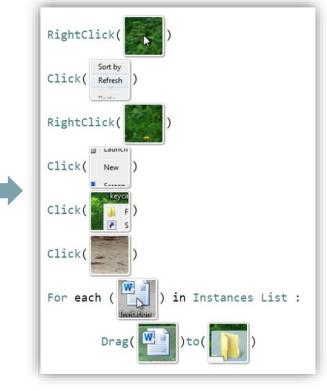
• Sniffer

Video

Log-file

INFO:root:6195671,000000.bmp,1405,357,no press, INFO:root:6195703,000001.bmp,1439,197,no press, INFO:root:6195734,000002.bmp,1463,168,no press, INFO:root:6195781,000003.bmp,1480,144,no press, INFO:root:6195796,000004.bmp,1482,134,no press, INFO:root:6195859,000005.bmp,1482,132,no press, INFO:root:6195906,000006.bmp,1482,119,no press, INFO:root:6195937,000007.bmp,1482,117,no press, INFO:root:6196046,000008.bmp,1483,123,no press, INFO:root:6196062,000009.bmp,1503,168,no press, INFO:root:6196093,000010.bmp,1569,226,no press, INFO:root:6196140,000011.bmp,1593,241,no press, INFO:root:6196171,000012.bmp,1595,242,no press, INFO:root:6196296,000013.bmp,1595,243,no press, INFO:root:6196343,000014.bmp,1606,292,no press, INFO:root:6196375,000015.bmp,1620,316,no press, INFO:root:6196484,000016.bmp,1620,317,no press, INFO:root:6196531,000017.bmp,1620,320,no press, INFO:root:6196562,000018.bmp,1619,321,no press, INFO:root:6196671,000019.bmp,1618,321,no press, INFO:root:6196718,000020.bmp,1608,317,no press, INFO:root:6196750,000021.bmp,1606,315,no press, INFO:root:6196843,000022.bmp,1606,315,no press, INFO:root:6196875,000023.bmp,1603,313,no press, INFO:root:6196921,000024.bmp,1602,312,no press, INFO:root:6196984,000025.bmp,1601,310,no press, INFO:root:6197125,000026.bmp,1601,310,press left, INFO:root:6197250,000027.bmp,1601,310,no press, INFO:root:6197578,000028.bmp,1596,310,no press,

Sequence of basic actions

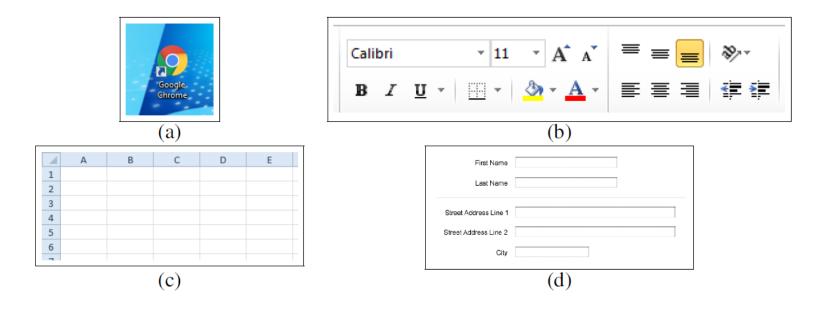


HILC gets follow-up input from user (a.k.a. Teacher):

- more positive examples
- remove false positive examples
- point out the visual cues
- add supporters

HILC allows users to add more positive examples, remove false positive examples, point out the visual and add supporters

Supporters

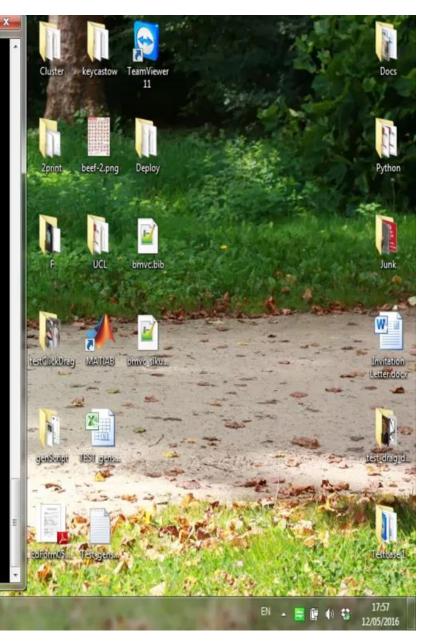


Teaching phase - How did we do it?

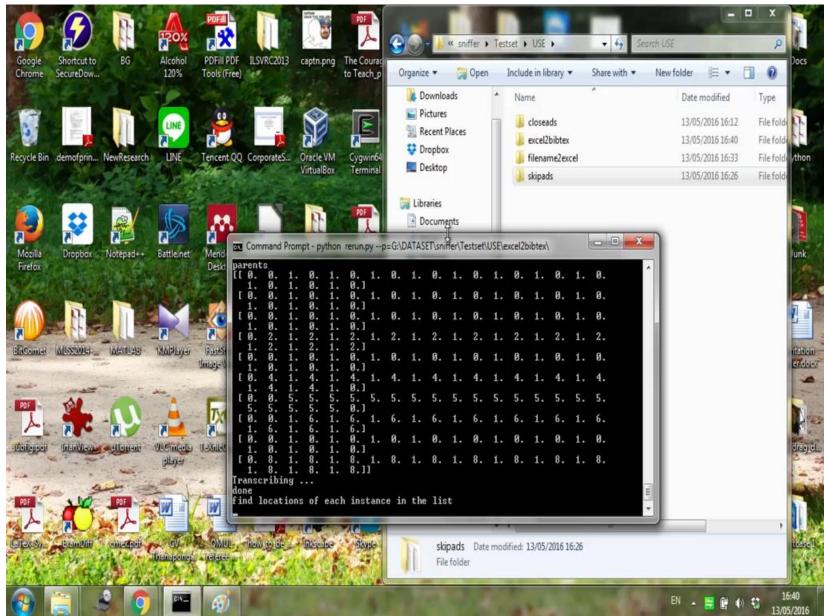
When and What to ask?

When and What to ask? (Linear tasks)

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When and What to ask? (Looping task)

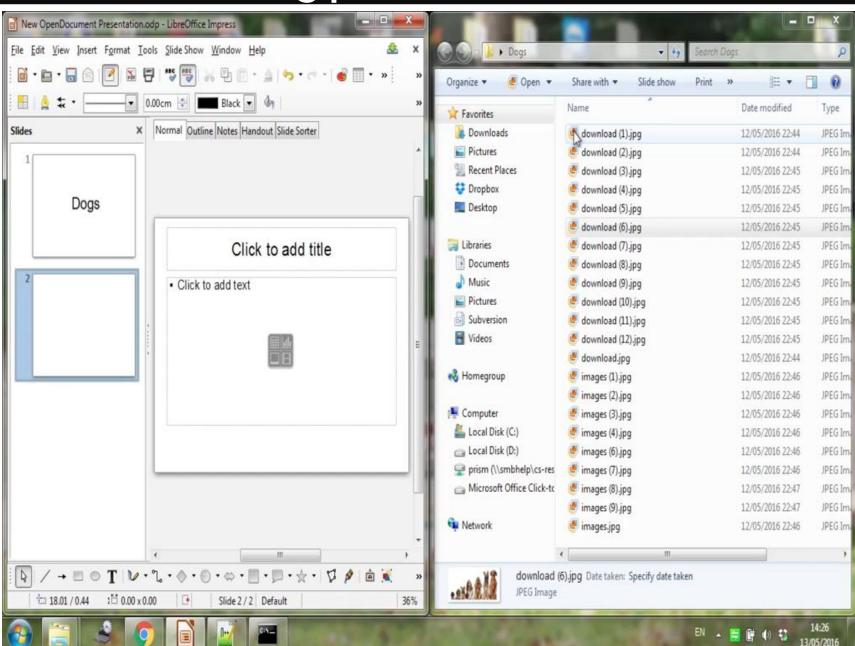


When and What to ask? (Monitoring task)

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Phase C: Running phase





Scenarios and experiments

	Basic Actions + Typing										
Scenario	Click	Click Drag	Double Click	Right Click	Typing	Transcription Reproducti		uction	Demonstration Time VS Refining Time (average)		
						Sikuli Slides	Our	Sikuli Slides	Our	Sikuli Slides	Our
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2 Turn on High-Contrast-Mode (Linear)	6	1	0	0	0	√ *	~	√ **	1	27s/10m	27s/170s
3 Remote access with Team Viewer (Linear)	11	0	0	0	4	✓*	~	X	1	40s/∞	40s/4m
3.2 Remote access with Team Viewer (Linear)	13	0	0	4	0	√ *	~	×	1	37s/∞	37s/7m
4. Skip YouTube ads (Monitoring)	1	0	0	0	0	X	~	×	1	N/A	10s/5.5m
5. Close YouTube ads (Monitoring)	1	0	0	0	0	X	✓	×	✓	N/A	12s/6.9m
6. Create slides out of jpgs folder (Looping)	2x	1x	0	0	0	X	~	X	✓	N/A	35s/10m
7. Create spreadsheet of filenames (Looping)	4x	2x	0	0	4x	×	✓	×	✓	N/A	60s/6.6m
8. Create BibTex from spreadsheet (Looping)	9x	0	0	0	8x	×	✓	×	✓	N/A	86s/12.5m
9. Move MSWord files to a folder (Looping-Video)	4	1x	0	2	0	×	✓	×	 ✓ 	N/A	25s/ 22m

Table 1. User study on our system compared to Sikuli Slides. Scenario 3.2 is an alternative way to perform Scenario 3, without pressing shortcut key combinations that Sikuli Slides is known to be missing. Nevertheless, we eventually realized that Sikuli Slides isn't detecting the right click actions either. (\checkmark = successful, \checkmark * = partially successful, \checkmark ** = can be successful with guidance from the operator, X = can not succeed at the task at all). x represents the number of repeated loops needed to complete the task. Please note that 90% of the refining time for Task 9 is offline - devoted to the time spent on processing video to produce the log-file.

<u>Limitations</u>

- HILC is not aware of off-screen objects. because it only looks at a screenshot image.
- Scrolling is currently not supported.
- HILC is not aware of system state, hence it only relies on a fixed time delay between basic actions.
- HILC relies on having a sniffer, but we have preliminary results from just videos of the GUI.

Take home messages

• Computer Vision.

• 3 Phases.

• Follow-up questions.

Thank you

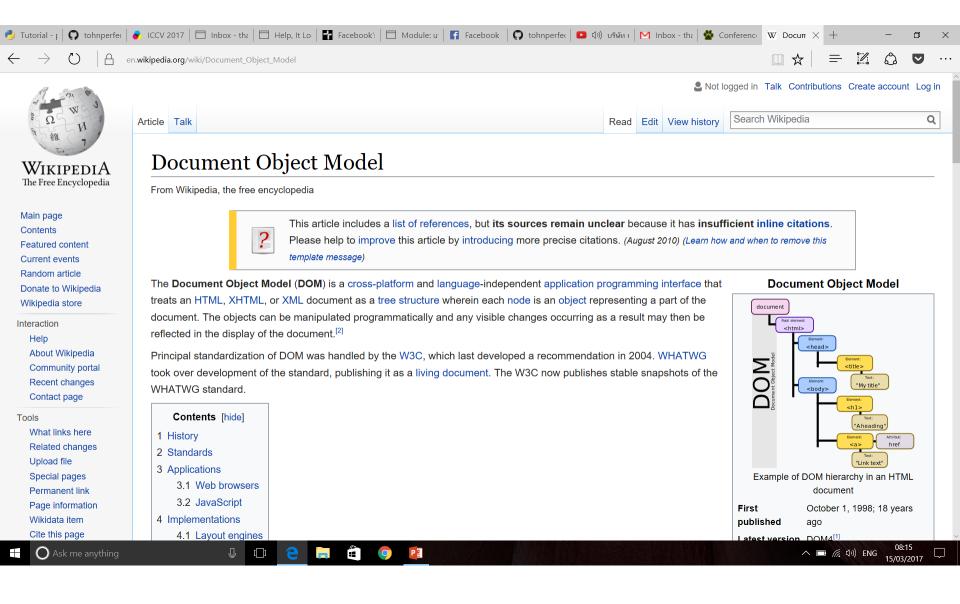
Q&A



For more information and code please visit

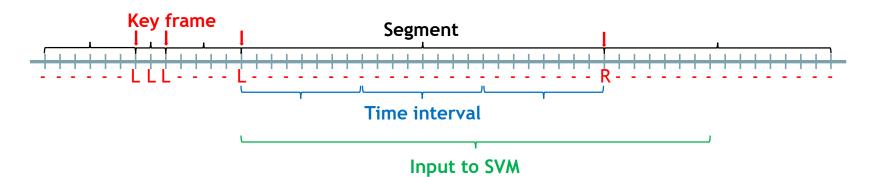
http://visual.cs.ucl.ac.uk/pubs/HILC/

Extra slides



Demonstration Phase - How did we do it?

- The log file unifies inputs from both video and sniffer
- Transcribe input log-file
 - Viterbi Algorithm
 - Unary potential is computed using SVM + Random Forest
 - Pairwise potential encourages segments from the same basic action to follow the order



Basic actions = {Click, Double Click, Click Drag, Right Click}